## Exhibit C

## BEFORE THE

## UNITED STATES INTERNATIONAL TRADE COMMISSION

In the Matter of: ) Investigation No.

CERTAIN ELECTRONIC DEVICES ) 337-TA-714

WITH MULTI-TOUCH ENABLED )

TOUCHPADS AND TOUCHSCREENS )

Hearing Room A

United States

International Trade Commission

500 E Street, Southwest

Washington, D.C.

Wednesday, February 16, 2011

## VOLUME II

The parties met, pursuant to the notice of the Judge, at 9:00 a.m.

BEFORE: THE HONORABLE PAUL J. LUCKERN

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OPEN SESSION 1 JUDGE LUCKERN: Okay. Go ahead, 2 3 counsellor. We're on the public record. 4 MS. MEHTA: Thank you, Your Honor. 5 CROSS-EXAMINATION 6 BY MS. MEHTA: Good morning, Dr. Westerman. I would 7 0. 8 like to step back. If you could please 9 describe your education after high school for 10 the record. In 1994 I received a Bachelor of 11 Α. 12 Science in electrical engineering from Purdue 13 University with highest distinction, and in 14 1999 I received a Ph.D. in electrical and 15 computer engineering from the University of 16 Delaware. 17 Thank you. When you got your Ph.D. 0. 18 from the University of Delaware, did you do a 19 dissertation? 20 Yes. Α. 21 And what was that on? 0. It was entitled: Path tracking finger 22 Α. 23 identification and chordic manipulation on a 24 multi-touch sensitive surface. 25 Q. If you will turn to your binder to tab

1 RX-639. Dr. Westerman, do you recognize
2 RX-639?

Yes. This is my Ph.D. dissertation. 3 Α. 4 MR. DeBRUINE: Your Honor, just a 5 moment, I am looking at RX-639 and I am not 6 seeing Bates numbers on this document. 7 MS. MEHTA: There is no objection to 8 this document. We identified it to you two 9 days ago and received no objection. 10 JUDGE LUCKERN: Speak up, please. 11 MS. MEHTA: I'm sorry, Your Honor. 12 There was no objection to this document. We 13 can give Mr. DeBruine a moment to check that. 14 JUDGE LUCKERN: Sure. 15 MR. DeBRUINE: That's correct, Your 16 Honor, I'm sorry. 17 JUDGE LUCKERN: All right. Go ahead, 18 counsellor. 19 MS. MEHTA: Thank you, Your Honor. 20 BY MS. MEHTA: 21 Q. Now, Mr. Westerman, or Dr. Westerman, 22 when you worked on your Ph.D. thesis, did you 23 look at work that had been done in the field of 24 touch prior to your thesis? 25 Yes, I did a search of both the patent Α.

and academic literature for other touch
 surfaces at the time.

3 Q. If you would turn to page RX-639.064.
4 And if you could review the first full
5 paragraph.

6 How does this paragraph, that begins 7 with the words "some devices on the market," 8 how does that paragraph relate to your 9 testimony a moment ago that you reviewed some 10 patent and publication literature in preparing 11 your thesis?

12 A. Well, I encountered the Bisset patent 13 and several other -- several single finger 14 touchpad technologies that use what we call 15 projective sensing, where they -- the signal 16 gets summed along each row electrode and each 17 column electrode.

18 So you only get a signal -- you only 19 get a measurement for the total signal in a row 20 or the total signal in a column. You don't get 21 the measurement at the intersections of the 22 rows and columns.

Q. Now, Dr. Westerman, in that answer you referred to the Bisset patent. You understand that's the patent that's at issue in this case? 1 A. Yes, I do.

2	Q. Okay. Now, you were describing the
3	technique of that patent. What was it that you
4	were trying to convey in your thesis with
5	respect to the Bisset and Kasser patent that's
6	at issue in this case?
7	A. Well, I was trying to convey that they
8	were not practical for multi-finger
9	applications because of a number of ambiguities
10	that developed, and I show these on the figures
11	on the next page.
12	Q. Chris, if we could have the figures on
13	the next page, please.
14	Dr. Westerman, using the figures on
15	RX-639.065, could you explain in a bit more
16	detail what you mean about the method not being
17	practical?
18	A. Well, here, for instance, we have four
19	fingertips in different diagonal arrangements
20	on a touch surface, as shown in the grid. And
21	over on the sides you can see the projection,
22	the row and column sum projections.
23	And while in these cases there are

24 still four peaks visible in sub-diagrams A, B,

 $25\ \text{and}\ \text{C}\,,$  in the rows and in the columns, the row

1 and column projections are really identical.

2 So we really lost information and we 3 can't tell whether the fingers are, you know, 4 have, basically which diagonal orientation they 5 have.

6 In the case of two fingers, this would 7 mean like if you have two fingers that are 8 diagonal, you can't tell if they are really 9 this way or this way (indicating) at the 10 ghosted corners of the diagonal.

11 So that's one set of ambiguities that 12 arises. And in diagram D it is showing when 13 the fingers get closer together, they can still 14 be distinguished in the 2D image, but in the 15 row and column projections, they are already 16 merging. So the resolution isn't as good.

17 And then in figure, two pages after, I 18 show another set of problems with projection 19 sensing schemes, which are inclusion problems. 20 Especially you can see in figure D there, 21 again, this is page .067, the fingers and palms 22 that are in the same columns are really kind of 23 occluding one another. They are all getting 24 added together, and we can't even count. In 25 the row and column projections that appear on

1 the side, you can't even count how many peaks
2 there are and know how many fingers or palms
3 are on that surface.

4 So --

5 Q. Sorry. Go ahead.

A. So, you know, with more and more
7 possible touches, that ambiguity is worsened to
8 the point where, you know, a projection sensing
9 system is just -- can't really handle things.
10 Q. Now, Dr. Westerman, did you come up
11 with a solution or an approach to address those
12 problems?

13 A. Yes. My Ph.D. advisor and I, first we 14 built an imaging sensor that could sense the 15 capacitance at each point in a two-dimensional 16 grid, so we got a true two-dimensional array of 17 sensing and not just row and column sensing.

18 Q. And when you had a full

19 two-dimensional array of sensing, what did that
20 generate in terms of data?

21 A. Well, it generated these images that 22 look sort of like paw prints of the hand, and 23 then we went on and in later chapters of the 24 dissertation, I explain how to do analysis of 25 these images, grouping the pixels into objects,

1 tracking the objects over time, and identifying 2 them as fingers or palms or thumbs, and so on, 3 and then extracting gestures and typing 4 information from their motions. Now, these two-dimensional images that 5 Ο. 6 you just described, how does that relate to 7 Apple's current multi-touch technology? A. Well, all of Apple's current 8 9 multi-touch products use two-dimensional 10 multi-touch imaging. And how does that multi-touch imaging 11 Ο. 12 relate to the ambiguities that you discuss with 13 respect to the Bisset and Kasser patent in your 14 thesis? 15 Α. It doesn't suffer from those 16 ambiguities, so we can -- which means that, you 17 know, people can use as many fingers 18 potentially as they like on our products. 19 O. Now, Dr. Westerman, you were 20 describing your thesis. After you completed 21 your thesis and your Ph.D., what did you do 22 next? 23 My Ph.D. advisor, John Ellias, and I Α. 24 founded, immediately founded a startup called

25 FingerWorks. And over about 18 months, we