

# **EXHIBIT L**



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**Armstrong**

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**(54) 3D CONTROLLER WITH VIBRATION**

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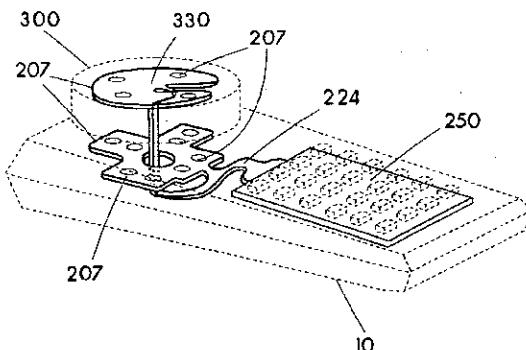
**ABSTRACT**

A hand operated controller or converter structured for allowing hand inputs to be converted or translated into electrical outputs, the controller structured with a plate or platform moveable relative to a base or housing about two mutually perpendicular axes generally parallel to the platform to effect a plurality of sensors for defining output signal(s) based on movement of the platform. The sensors each have an electrically active activator spatially separated from an electric contact surface. A tactile feedback motor with shaft and offset weight is mounted as a component of the controller for providing vibration to be felt by a hand operating the controller. In some embodiments the sensors are pressure sensitive variable output sensors.

**33 Claims, 40 Drawing Sheets**

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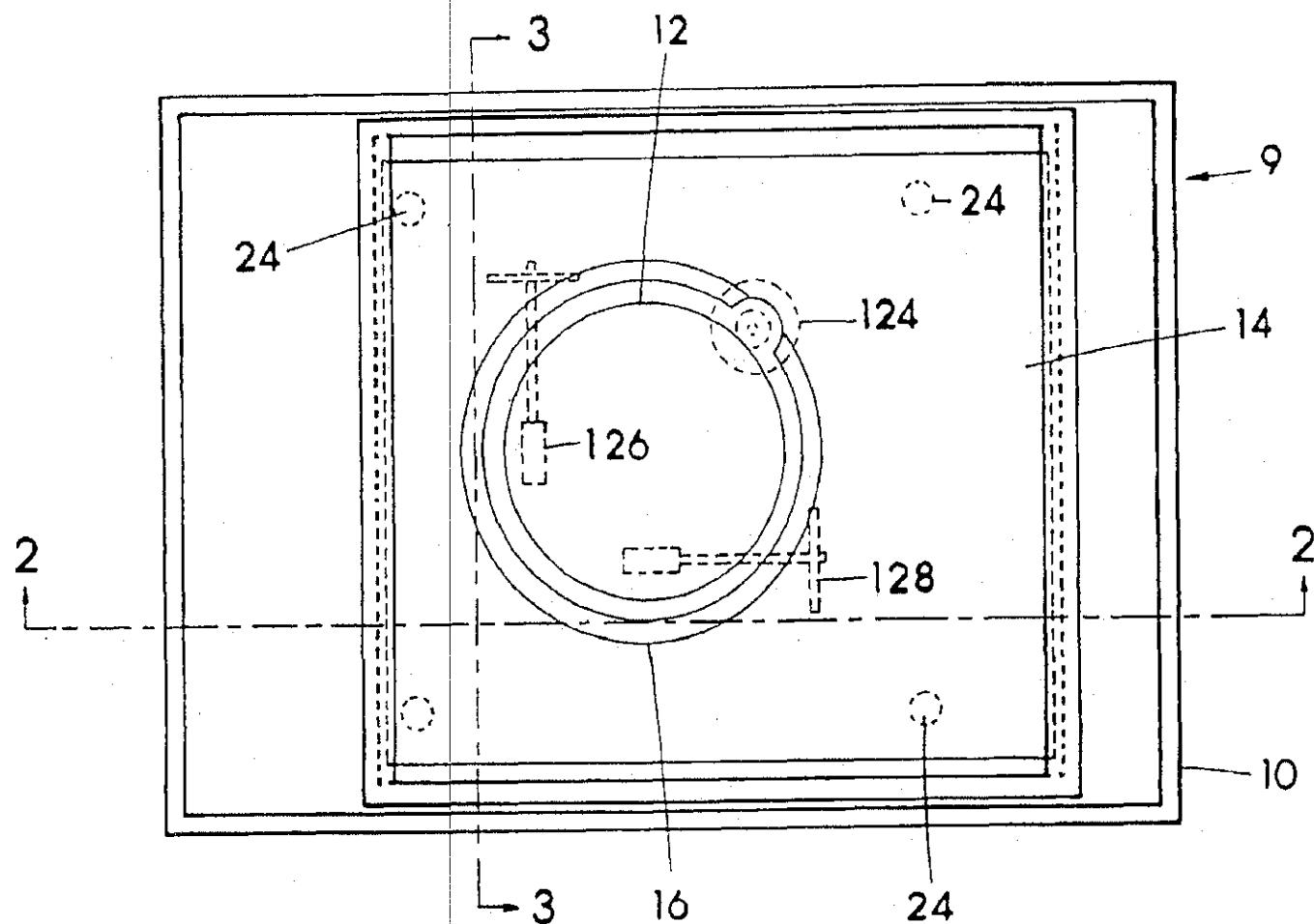


FIG. 1

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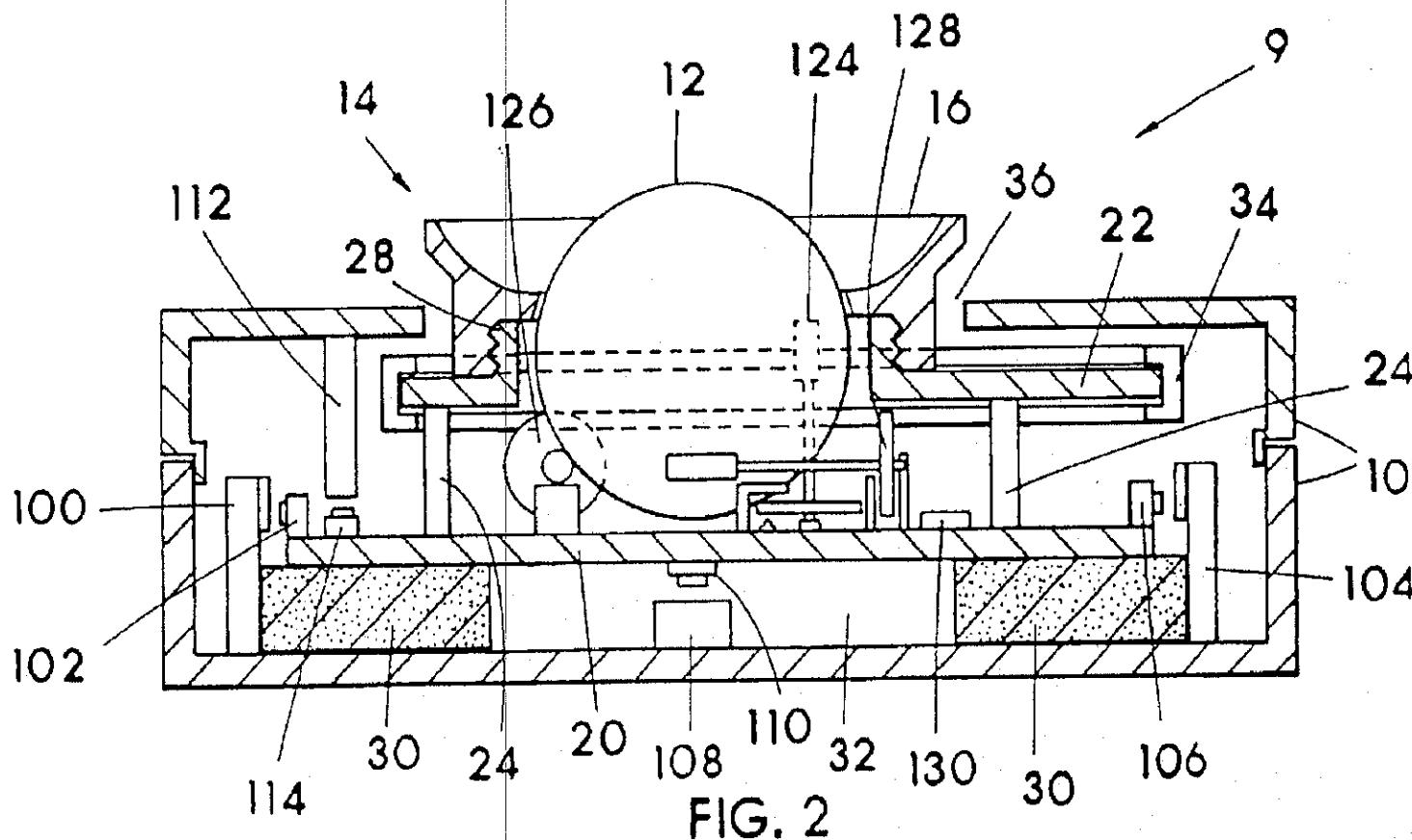
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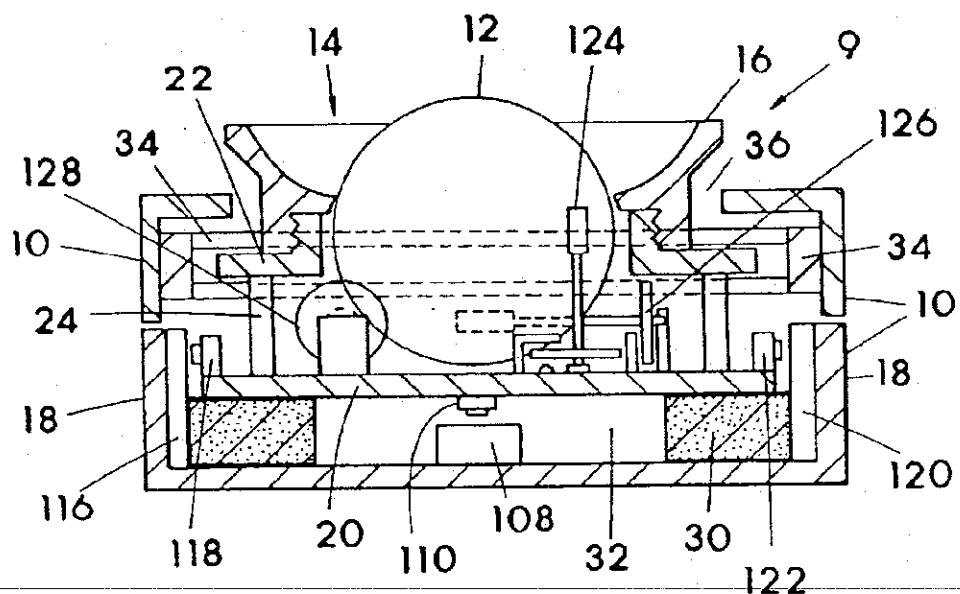


FIG. 3

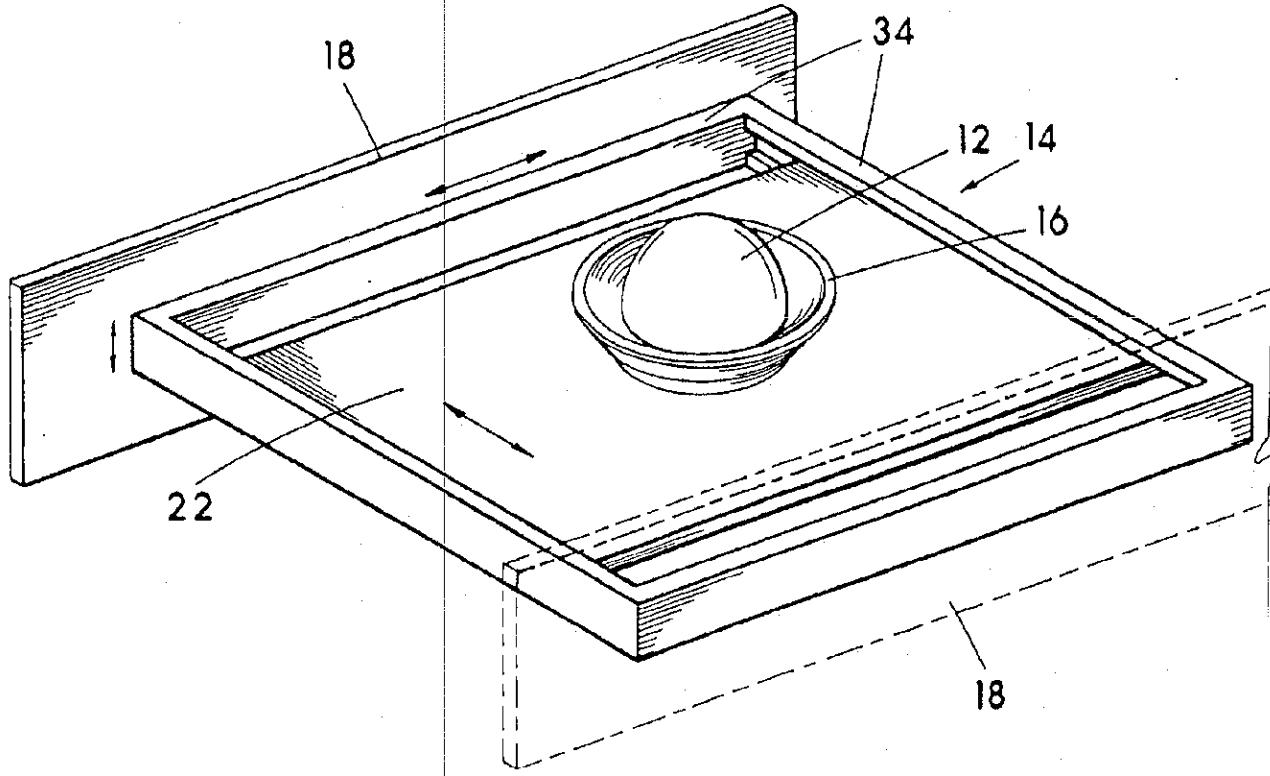


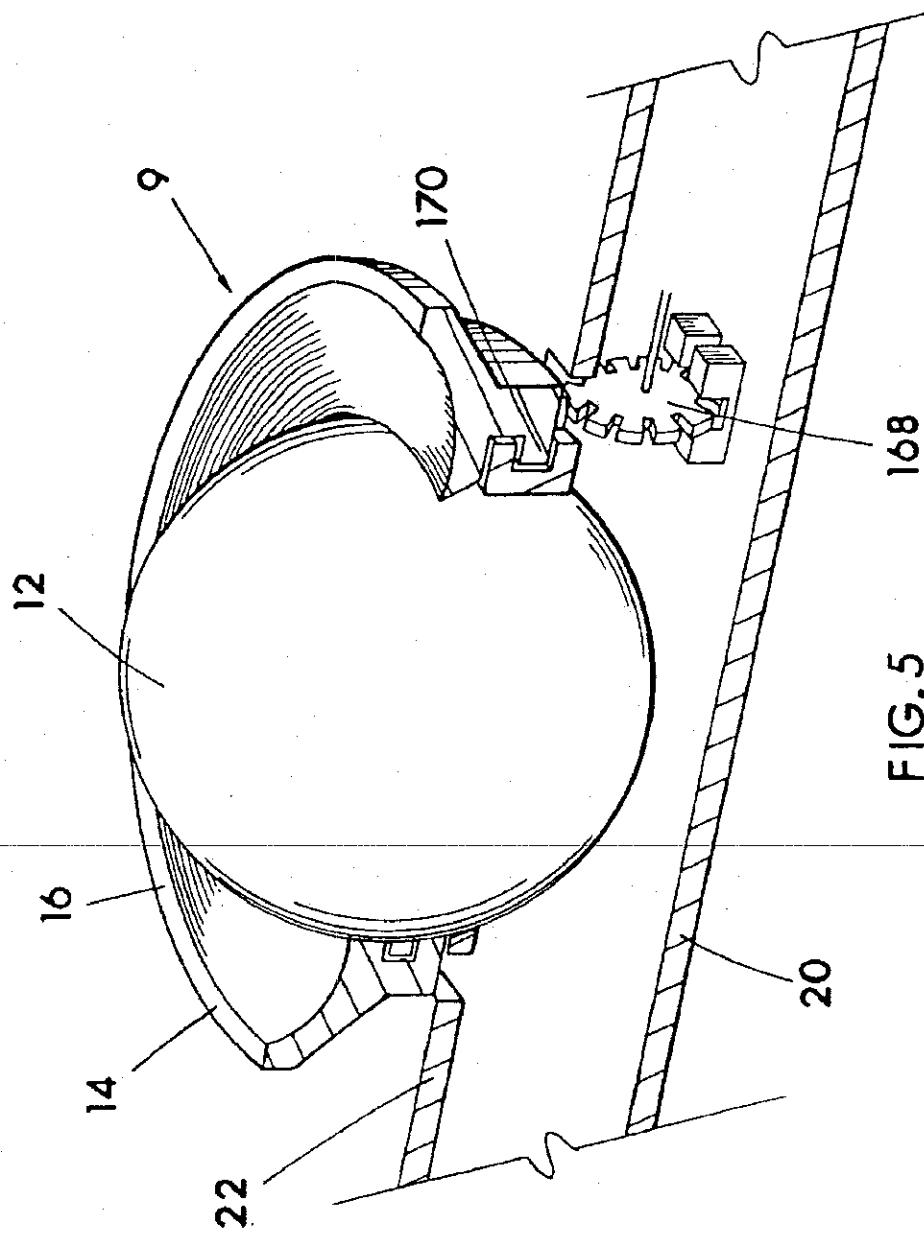
FIG. 4

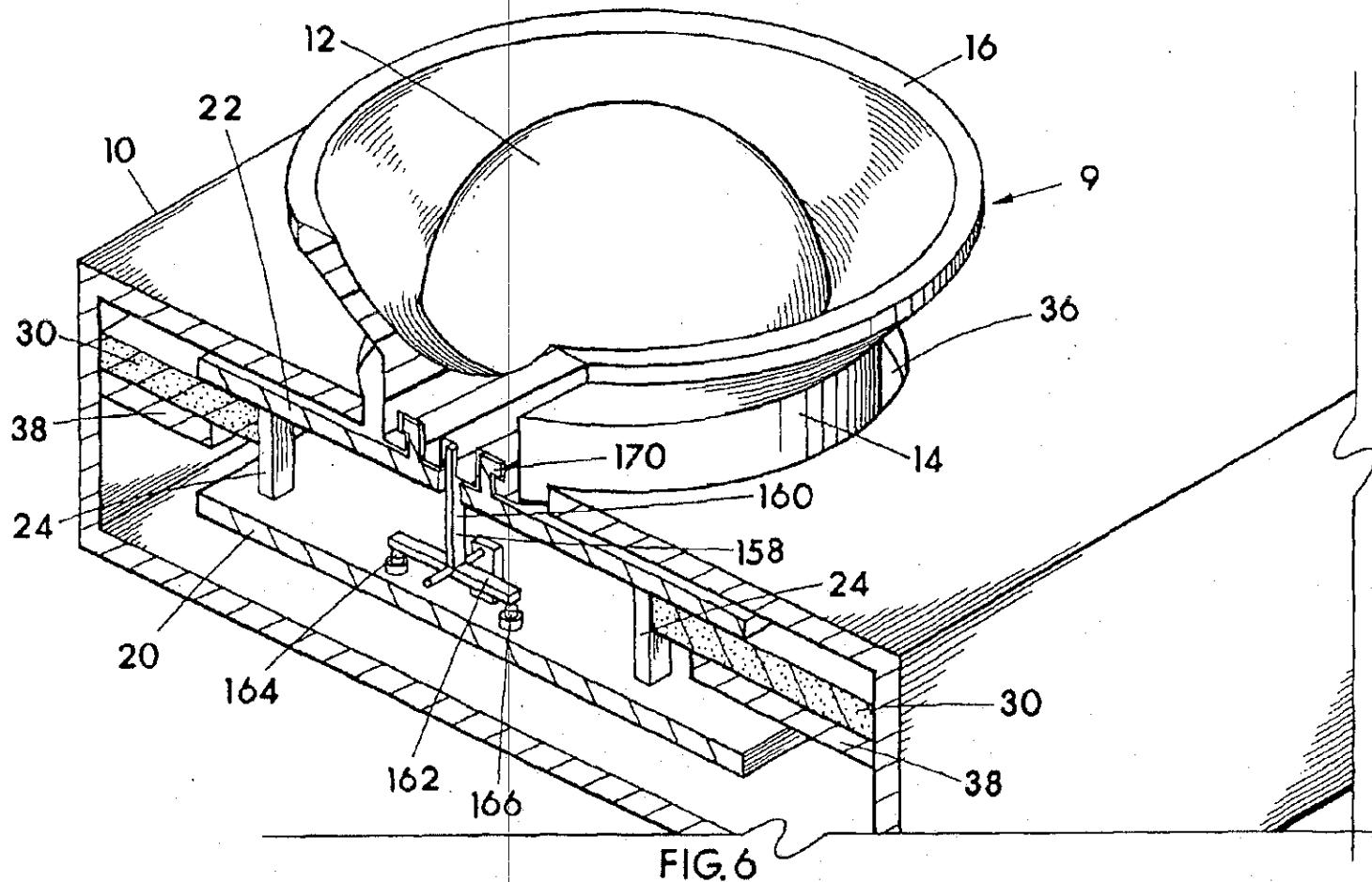
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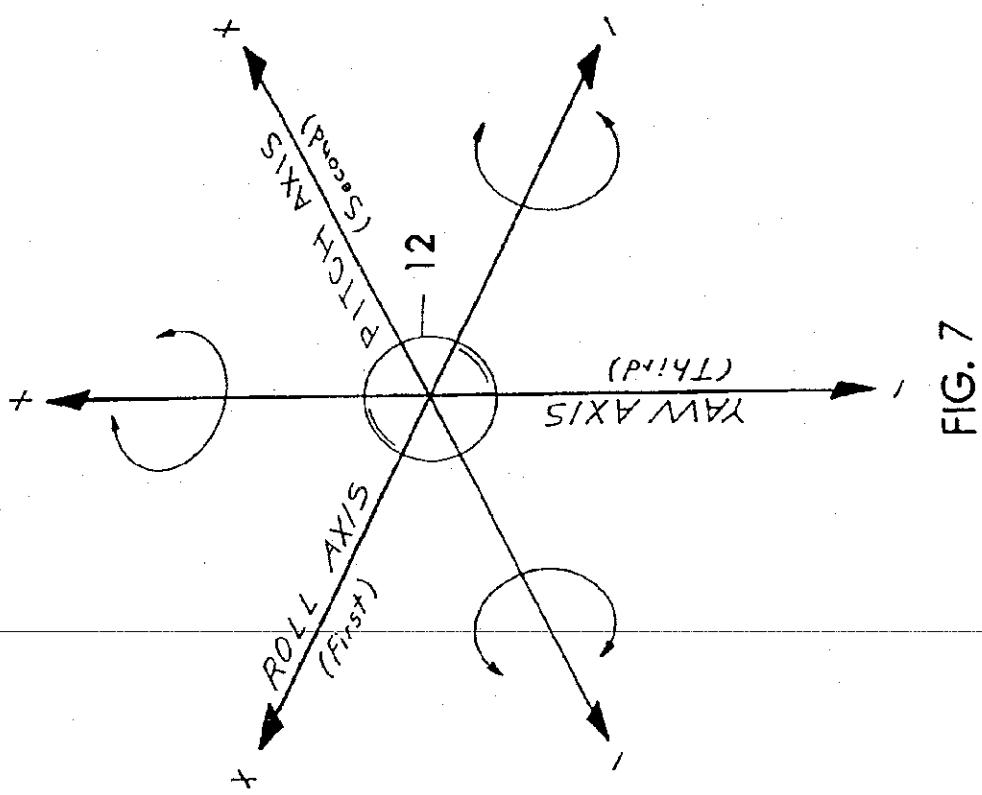


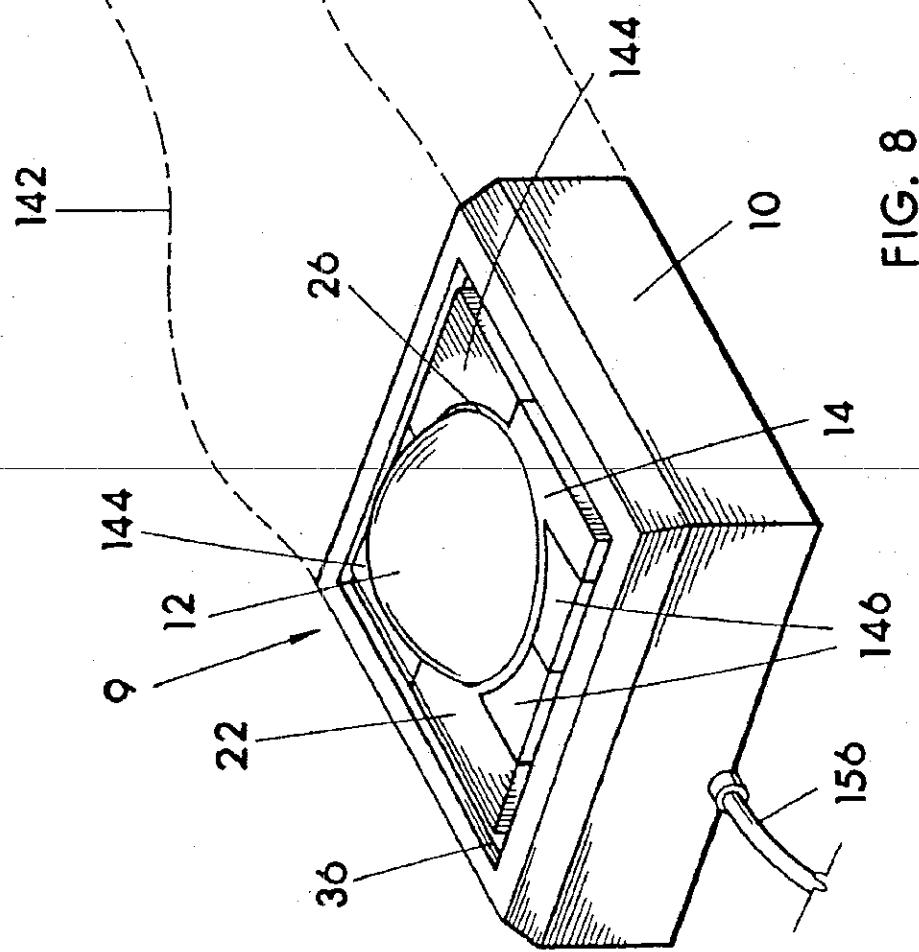
FIG. 7

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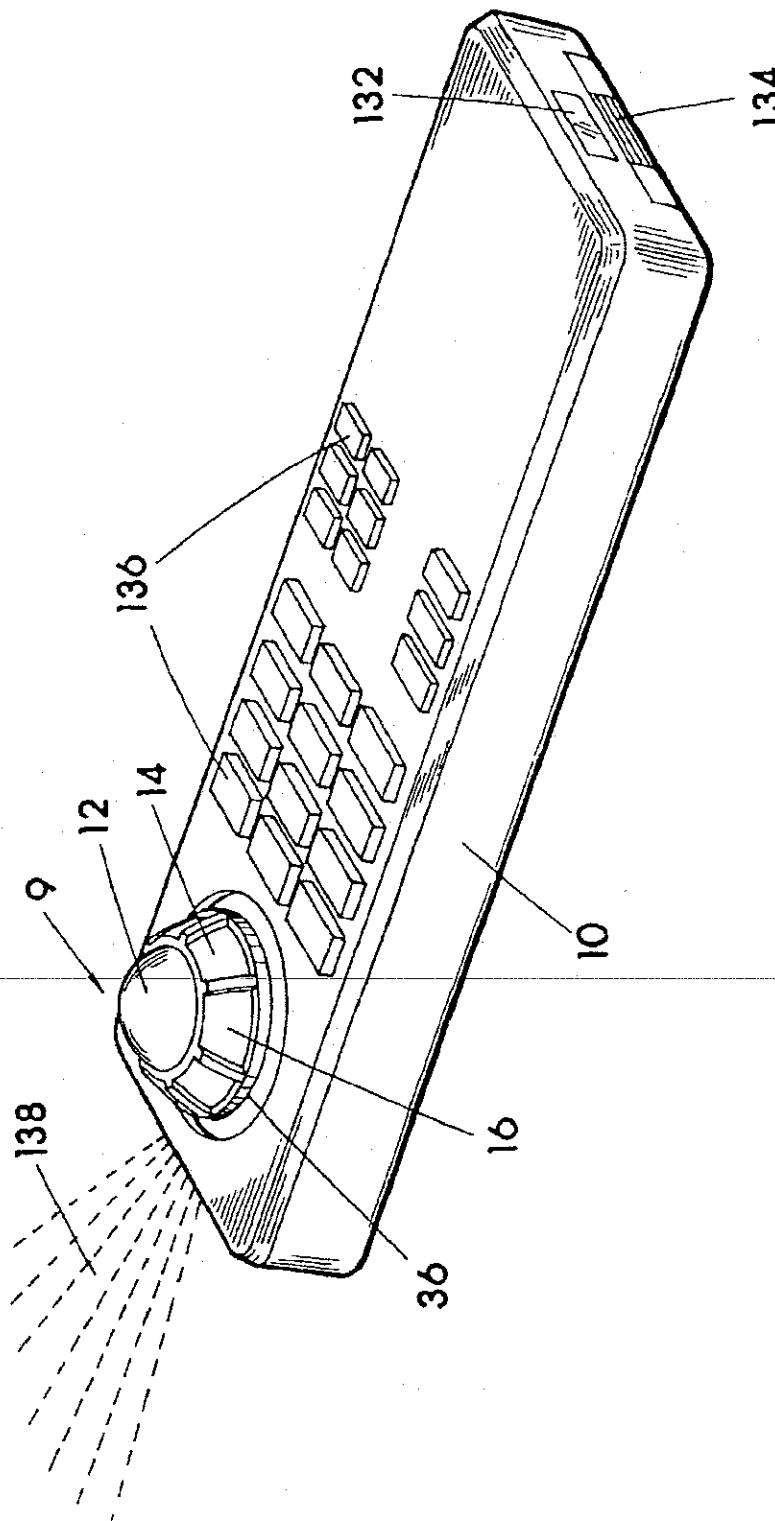


FIG. 9

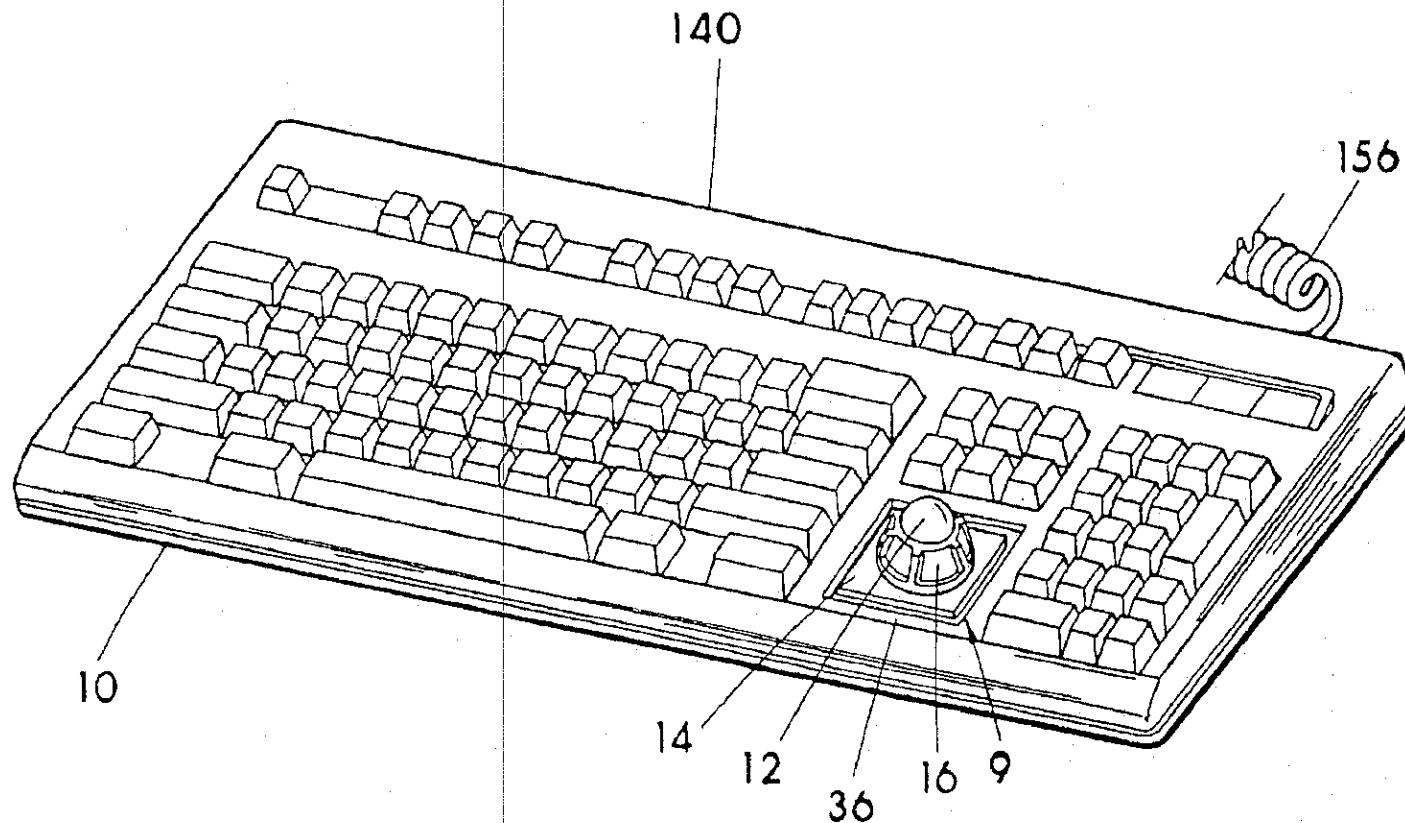


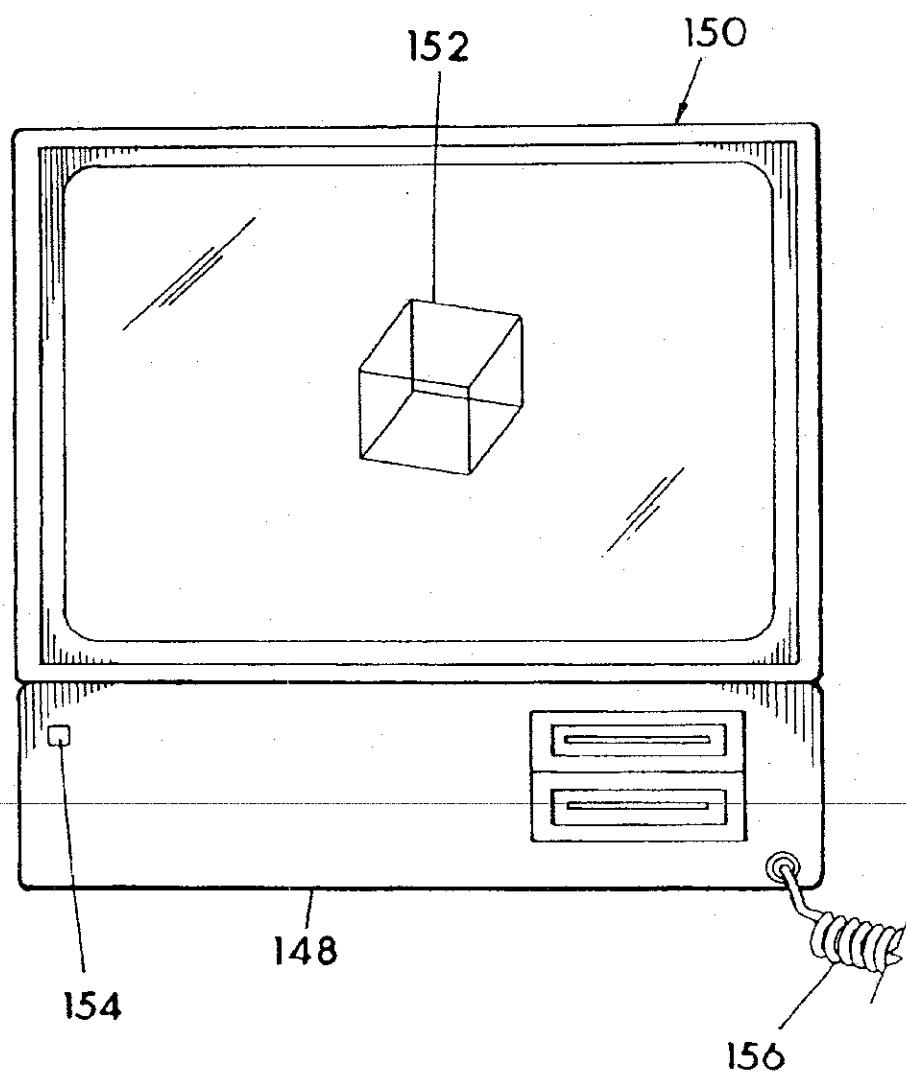
FIG. 10

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**FIG. 11**

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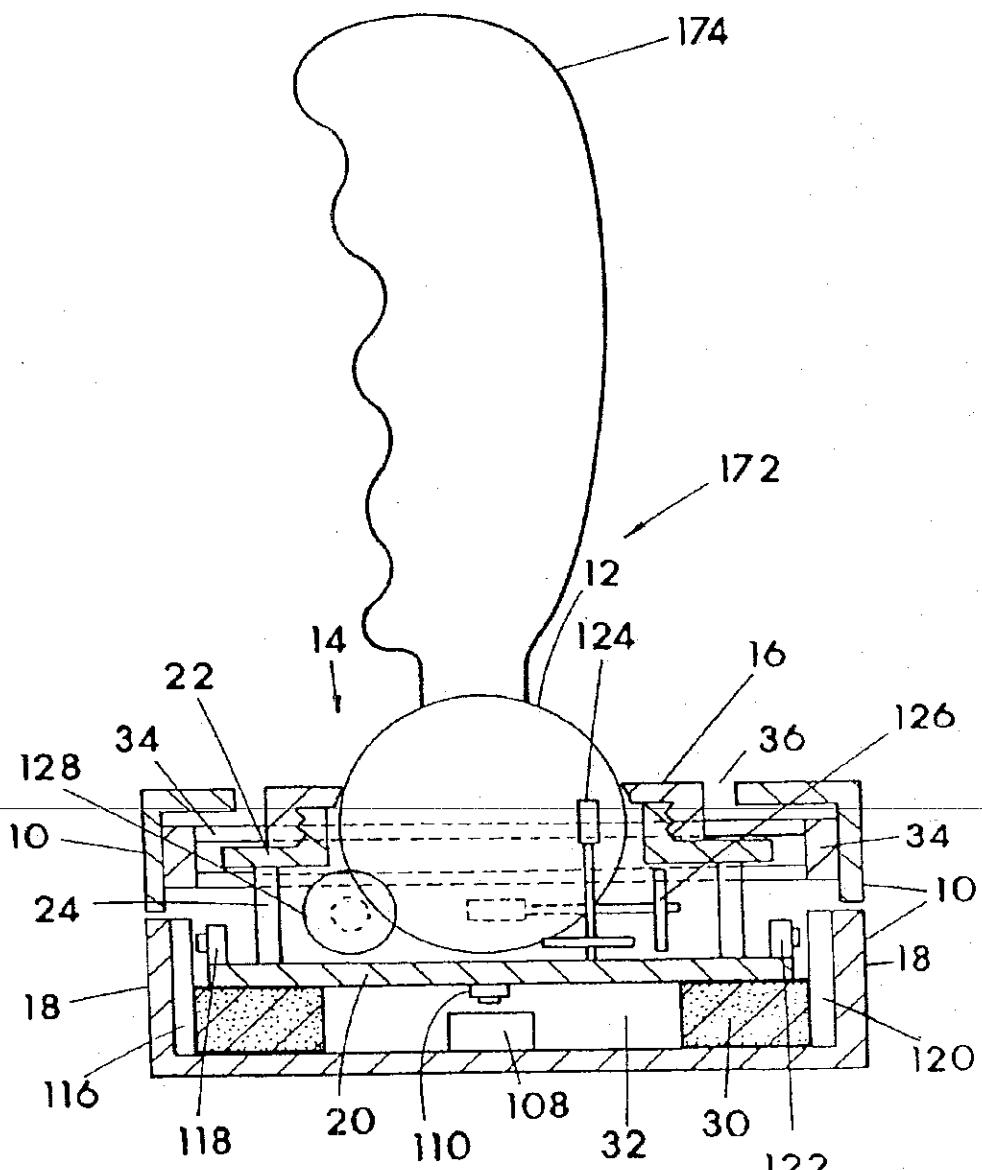


FIG. 12

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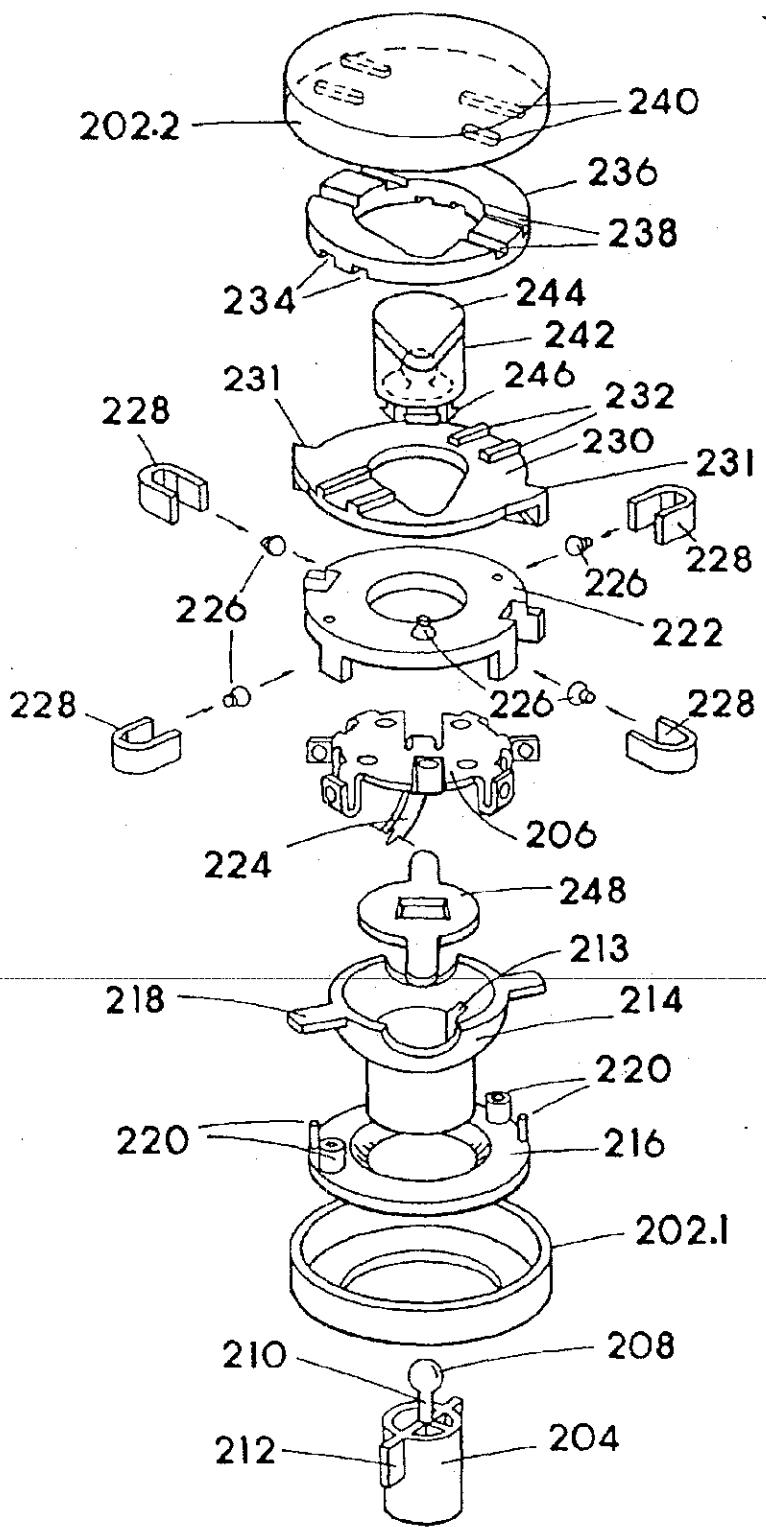


FIG. 13

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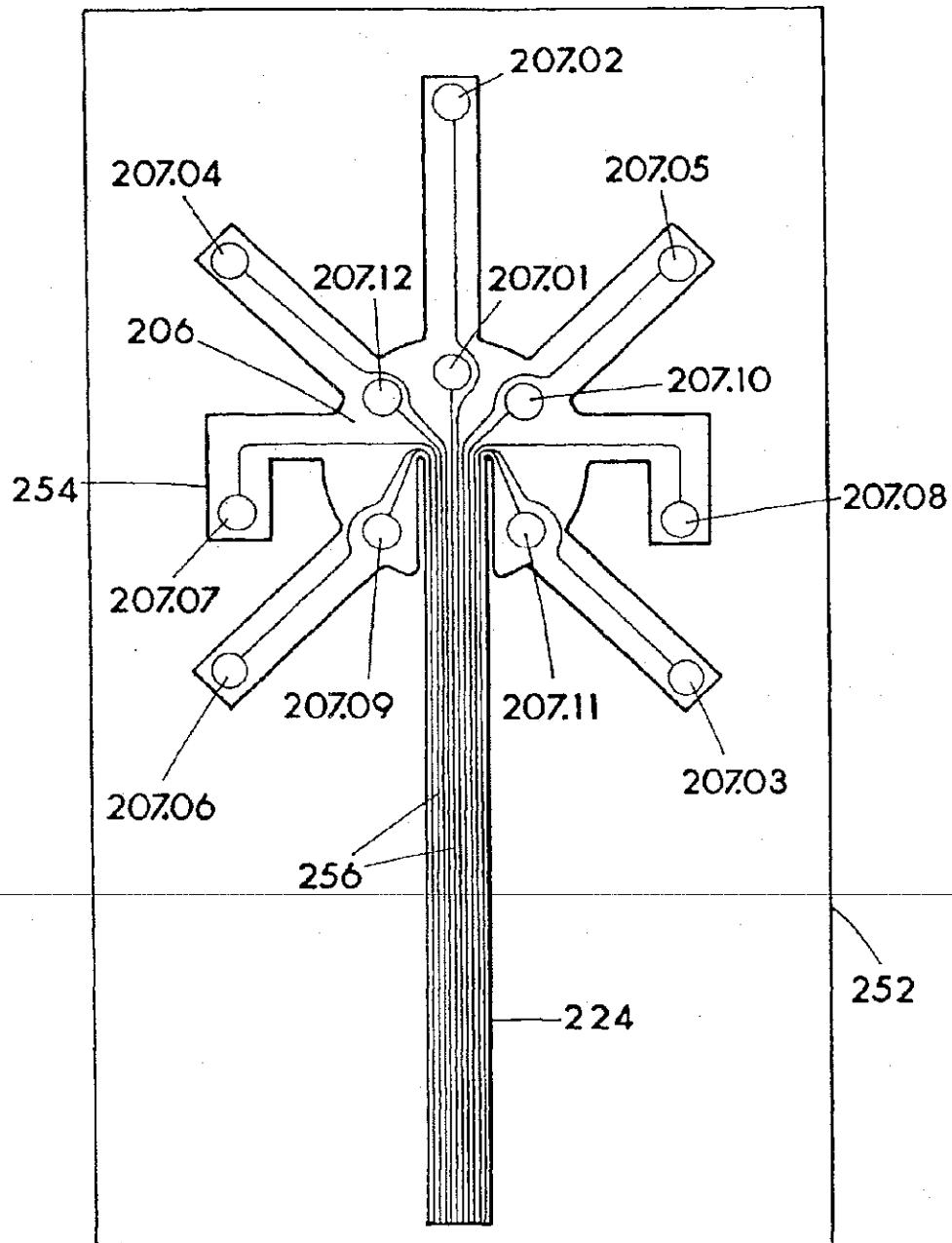


FIG. 14

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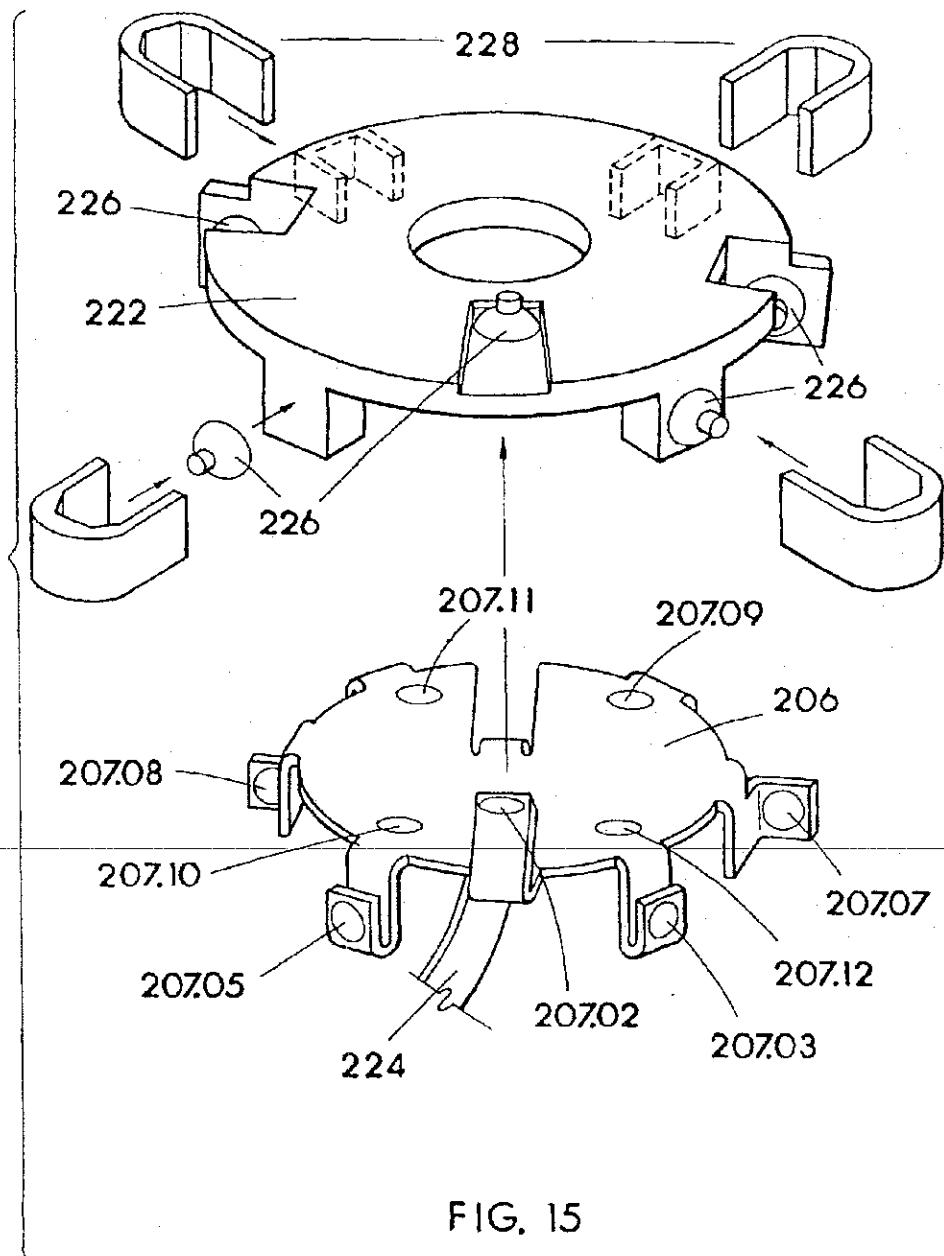


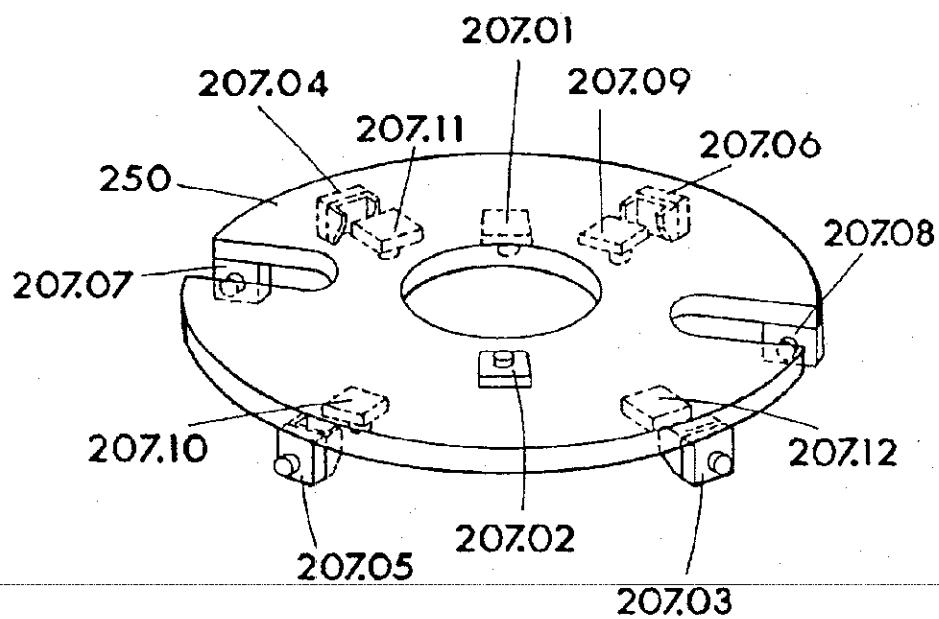
FIG. 15

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**FIG. 16**